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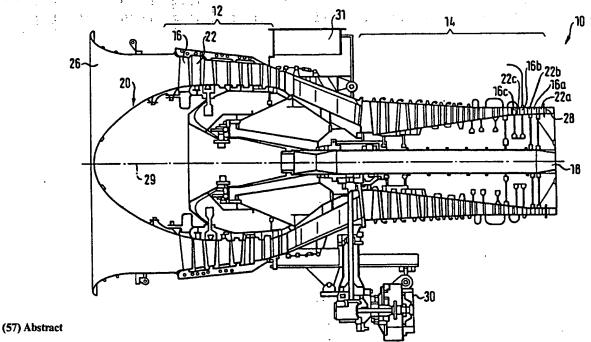
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(54) Title: PROCESS AND DEVICE FOR MONITORING AND FOR CONTROLLING OF A COMPRESSOR



A process and a device for monitoring and controlling a compressor (10) by measuring pressure fluctuations within at least one stage of the compressor (10) in the region of the housing (24) of the compressor (10) by means of at least one pressure sensing device (32), deriving a frequency signal which comprises at least one characteristic peak (70) in a region of a characteristic frequency assigned to one of the compressor stages (12, 14) and determining at least one peak parameter indicative of the operational status of the compressor (10), and generating a status change signal in case the peak parameter lies beyond a predetermined value range, which is used for controlling the compressor (10).

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#### PROCESS AND DEVICE FOR MONITORING AND FOR CONTROLLING OF A COMPRESSOR

#### FIELD OF THE INVENTION

The present invention relates to a process and a device for monitoring and controlling of a compressor, said compressor comprising a rotor and a housing, said rotor being rotatably mounted within said housing for rotation about a rotational axis with variable or constant rotational speed, said compressor further comprising at least one compressor stage, each of said at 10 least one stages comprising a row of rotor blades mounted on said rotor and being arranged one following the other in a circumferential direction with respect to said rotational axis and of a row of stator blades mounted on said housing and being arranged one following the other in a circumferential direction with respect to said rotational axis.

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The invention provides for an early detection and reporting of changes in blade-loading for either multi- or single-stage compressors with the possibility of being able to control the compressor in accordance with the reported changes. A compressor may be operated as an isolated unit (for example as large pump or an example as large pump or the second sec 20 process compressor in the chemical or petroleum industry) or in conjunction with a power-turbine engine, as would be the case in a power plant operation. The compressor may further be part of a gas turbine used for driving aeroplanes, ships or large vehicles. The compressor may be a radial type compressor or preferably an axial type compressor.

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#### BACKGROUND OF THE INVENTION

Compressors consist of a series of rotating or stationary blade rows in which the combination of a rotor (circular rotating blade row) and a stator (circular stationary blade row) forms one stage. Inside the rotor, kinetic energy 30 is transferred to the gas flow (usually air) by the individual airfoil blades. In the following stator, this energy is manifested as a pressure rise in the gaseous air as a consequence of deceleration of the gaseous air flow. This deceleration of the gaseous air flow is induced as a result of the design of the stator section. The pressure ratio (exit pressure/inlet pressure) of a single stage is limited 35 because of intrinsic aerodynamic factors, so several stages are connected together in many turbo compressors to achieve higher pressure ratios than could be achieved by a single stage.

The maximum achievable pressure ratio of a turbo compressor is established by the so-called stability limit of the compressor given by the characteristic of the compressor and the gaseous air flowing through the compressor at any time. As the pressure in the compressor increases, the aerodynamic loading on the compressor blades must also increase. At full speed operation of a multistage compressor, the rear stages carry the majority of the aerodynamic load (and attendant stress), and the stability limit is established by the limits inherent in the design of these stages. When operating at lower speeds, the stability limit of the compressor is established by limitations deriving from characteristics related to the front stages of the compressor.

In the normal stable working range of a compressor stage, axial flow of gaseous air through all of the vane channels between the compressor blades takes place equally and continuously as the air volume is transported through the channels. However, a compressor stage can also operate in a state known as an unstable working range. In this unstable working range, a stall condition can be present in the interaction between the air flow and the airfoil blades which can contribute to substantial variations in the internal pressure profile of the compressor. These pressure variations can, in turn, cause substantial stress to the blades of the compressor. Ultimately, this stress can damage the blades if the compressor continues to operate in the unstable working range for any length of time. Operation in the unstable working range is inefficient at best and potentially destructive; this mode of operation should be avoided as much as possible.

The development of a stall in a stage of the compressor proceeds from the interaction of individual airfoil blades with the gaseous air flowing through the vanes associated with those individual blades. Ideally, the gaseous air fluid flow should be axially continuous through the compressor; however, high blade loads can induce localized disruptions to that continuous flow.

The air fluid flow around each blade has an associated flow boundary layer which covers each blade and coheres to the blade. The flow boundary layer associated with a rotor blade will rotate as an associated entity of the blade as the blade itself rotates. At the downstream edge of each blade, this flow boundary layer melds into an associated flow boundary entity known as the "delve region or wake region" which is characterized by a localized

reduction in both pressure and flow velocity. With increasing load, this wake region correspondingly will extend until a critical mass or size is achieved; when the wake region on the downstream edge of the blade achieves this critical size, it fractures or fragments into (1) a (new) smaller wake region which is still coherent with the blade and (2) a "flow boundary layer part" which physically separates from the wake region. Studies have indicated that these "flow boundary layer parts", separated from the rotor blades, move radially outwards from the axis of rotation due to centrifugal forces and collect at the inner circumferential surface of the compressor housing. This collection of separated flow boundary layer parts "swirls" and effectively establishes a turbulent fluid layer (or collection of swirled separated regions) at the inner surface of the housing; this turbulent fluid layer has associated stochastic pressure fluctuations which are useful in the present invention. For the purpose of this disclosure, this initial state associated with an increasing compressor loading will be termed as a "separated flow pre-stall".

With further increasing load, disrupted flow zones downstream of the blades expand in size and/or increase in number. Disruption of the continuous air flow through either groups of non-contiguous single-blade channels or whole characterized as a sort of "bubble-like" entity which, in general, moves circumferentially throughout the stage with a rotational speed up to 0.5 times with large blade heights, only the radially outer part of the blade channels is blocked and this situation is known as a "part span stall". With increasing load, the entire set of blade channels in a stage can be effectively blocked, resulting in an event and condition known as a "full span stall". In case of compressor stages having small overall diameters, "full span stall" can occur directly without transition through "part span stall" status.

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Another phenomenon, which may derive from rotating stall or also may occur suddenly with increased blade loading, is the "compressor surge". In this state, the whole circumference of one stage (usually the last one) has stalled (full span stall in the full blading). Then, the compressor cannot work any longer against the back- pressure of this one stage and the flow in the compressor breaks down. The high pressure gas flows back from the outlet to the compressor intake until the pressure at the compressor outlet is reduced enough so that a moderate blade load allows normal working again. When the

back pressure is not reduced, this changing operation will be continued. These fluctuations will take place with very low frequencies (typically a few Hertz) and will destroy the compressor within a short time of operation because the rotor is respectively shifted axially fore and aft. Furthermore, the compressor surge will be accompanied by fluctuations in the continuous overall air flow to the firing chamber in case of a gas turbine; these fluctuations can disrupt the environment in the firing chamber of the turbine in such a manner as to extinguish the "flame" in the firing chamber or (in some rare instances) establish the prerequisite environment for a backfire of the turbine through the compressor. A compressor should not be operated under such conditions; at best, operation will be inefficient for those stages wherein stall effects occur.

On the other hand, it is desirable to operate a compressor in an optimally efficient manner (that is as close as possible to the appropriate maximum obtainable mass flow rate given by the overall status of the compressor). Contemporary turbo engines are usually equipped with fuel or energy control systems which measure and output a variety of operating parameters for the Chemical Control systems are highly accurate pressure and such control systems are highly accurate pressure The second by the second sensing devices or systems. For example, pressure measuring systems are the second described in US Patent No. 4,322,977 entitled "Pressure Measuring System", filed May 27, 1980 in the names of Robert C. Shell, et al; US Patent No. 4,434,644 issued March 6, 1984; entitled "Pressure Ratio Measurement System", in the name of Frank J. Antonazzi; US Patent No. 4,422,355 issued December 27, 1983, entitled "Pressure Transducer"; US Patent No. 4,449,409, 25 entitled "Pressure Measurement System With A Constant Settlement Time", in the name of Frank J. Antonazzi; US Patent No. 4,457,179, issued July 3, 1984, entitled "Differential Pressure Measuring System", in the name of J. Bluish et al and US Patent No. 4,422,125, issued December 20, 1983, entitled "Pressure Transducer With An Invariable Reference Capacitor", in the name of 30 Frank J. Antonazzi et al.

US Patent 4,216,672 to Henry et al, discloses an apparatus for detecting and indicating the occurrence of a gas turbine engine stall which operated by sensing sudden changes in a selected engine pressure. A visual indication is also provided.

US Patent 4,055,994 to Roslyng et al discloses a method and a device of detecting the stall condition of an axial flow fan or compressor. The method and

device measure the pressure difference between the total air pressure acting in a direction opposite to the direction of the revolution of the fan wheel and a reference pressure corresponding to the static pressure at the wall of a duct in substantially the same radial plane.

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US Patent 4,618,856 to Frank J. Antonazzi discloses a detector for measuring pressure and detecting a pressure surge in the compressor of a turbine engine. The detector is incorporated in an analog to a digital pressure measuring system which includes a capacitive sensing capacitor and a 10 substantially invariable reference capacitor.

While a wide variety of pressure measuring devices can be used in conjunction with the present invention, the disclosures of the above-identified patents and the articles mentioned next are hereby expressly incorporated by 15 reference herein for a full and complete understanding of the operation of the invention.

をあって、 Response Organ (The article "Rotating Waves as a Stall Inception Indication in Axial (日本の本語) (現場) 森麓 Compressors" of V.H. Garnier, A.H. Epstein, E.M. Greitzer as presented at the and Barrier and Exposition" from June 11 to 14, 11 Section 20 1990, Brussels, Belgium, ASME Paper No. 90-GT-156, discloses the observation of rotating stall. In case of a low speed compressor, the axial velocity of air flow is measured by several hot wire anemometers distributed around the circumference of the compressor. From the respective sensor 25 signals, complex Fourier coefficients are calculated, which coefficients contain detailed information on the wave position and amplitude as a function of time of a wave traveling along the circumference of the compressor. These traveling waves are to be identified with rotating stall waves. In case of a high speed compressor, several wall mounted, high-response, static pressure transducers 30 are employed, from which sensor signals first and second Fourier coefficients are being derived. However, this direct spectral approach does not directly yield information on compressor stability, since the height of the rotating stall wave peak is a function of both the damping of the system and the amplitude of the excitation. To estimate the wave damping, a damping model is fitted to the as data for an early time estimate of the damping factor. By this technique, a rather short warning time may be available (in the region of tens to hundreds of rotor revolutions) to take corrective action (changing the fuel flow, nozzle area, vane settings etc.) to avoid compressor surge.

In the article "Fast Response Wall Pressure Measurement as a Means of Gas Turbine Blade Fault Identification" of K. Mathioudakis, A. Papathanasious, E. Loukis and L. Papailiou, as presented at the "Gas Turbine and Aeroengine Congress and Exposition" at Brussels, Belgium, from June 11-14, 1990, ASME Paper No. 90-GT-341, it is mentioned that rotating stall is accompanied by the appearance of distinct waveforms in the measured pressure, corresponding to a rotational speed which is a fraction of the shaft rotational speed.

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The systems known in the art cannot detect an unstable operating condition based on the preliminary indications of instability. They can only detect well established unstable conditions in an advanced state and, therefore, must avoid operation in the region where damage could result to the 15 compressor from the more subtle kinds of instability. In order to avoid operation in the region where damage could result to the compressor, prior art compressor control systems operate with a high safety margin; this margin is well below the maximum possible mass flow rate of the compressor. In effect, the prior art compressor must therefore operate in a less efficient and a less 20 economical mode than be realized with the subject of this invention. 在我的意思,我们也没有要把重要在这个生物的人的人的人的人的人。 在我们是不会的人的人的人

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Furthermore, the prior art control systems can detect an existing tendency of the compressor towards a stall condition or a surge condition only at a very short time before the actual occurrence of stall or surge. In many 25 cases there is not enough time left after the above detection to take corrective actions for avoiding stall or surge.

> The reduction of the risk of compressor stall and compressor surge is a further reason for the prior art compressor control systems to operate with the 30 high safety margin.

#### SUMMARY OF THE INVENTION

It is an object of the present invention to provide a process for monitoring of an axial compressor which is sensitive in detecting small changes in the flow 35 conditions of the axial compressor near the maximum mass flow rate.

It is a further object of the invention to provide a process for monitoring of an axial compressor which provides for an early warning of a compressor stall.

Another object of the invention is to provide a process for monitoring of an axial compressor allowing an online monitoring with fast response, using common calculation techniques for the signal evaluation.

One or more of these objects are solved by the process according to the invention, said process comprising the following steps:

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- measuring of pressure fluctuations within at least one of said compressor stages in the region of said housing by means of at least one pressure sensing device, each device delivering a sensor signal, respectively;
- b) deriving a frequency signal from each of said sensor signals, said frequency signal being indicative of amplitudes of frequency components of said respective sensor signals in a respective frequency interval;
- c) checking whether each of said frequency signals comprises at least one characteristic peak in a region of a characteristic frequency assigned to one of said compressor stages, respectively and determining at least one peak parameter indicative of the form of said characteristic peaks, said characteristic frequency being defined as the product of said rotational speed and the blade number of the rotor blades of the respective compressor stage;
  - d) generating a status change signal indicative of a change of operational status of said compressor in case of said peak parameter having a value lying beyond a determined value range.

According to the invention the characteristic peak is observed. This peak is sensitive to changes in the flow conditions near the maximum available mass flow rate. When the compressor is operating in a status characterized by a substantial distance from the maximum flow rate the wake regions of the rotating blades passing the pressure sensing device produce a pressure variation at that sensing device with the characteristic frequency. The frequency signal derived from the respective sensor signal shows a respective characteristic peak the form of which is defined by respective peak parameters (peak height, peak width or the like). It has been found that, with increasing

load approaching the mentioned maximum mass flow rate for the respective rotor frequency, the characteristic peak becomes more distinct (increasing height and/or increasing width) which may be attributed to the wake regions increasing with load. However, with further increasing load a decreasing characteristic peak is observed. This phenomenon is due to the separation of the region of the flow boundary layer in the area of the downstream edge of each blade into fragments called "flow boundary layer parts", these boundary layer parts being collected at the inner circumferential surface of the compressor, constituting a relatively thick layer with stochastic fluctuations. The pressure sensing device sensing the pressure fluctuations of this layer at the inner circumferential surface of the compressor delivers a sensor signal with increasing amount of background noise component and reduced periodic part component. Thus, in the above mentioned separated flow pre-stall condition, the characteristic peak decreases and in general vanishes since the stochastic 15 fluctuating layer at the inner circumference of the compressor increases and shields the pressure sensing device against the periodic pressure fluctuations due to the rotating wake regions of the rotating blades. In the pre-stall status there is essentially no blockage of the stage Only with further increasing load the pre-stall status evolves into a stall status (rotating stall; part span stall; full Los fires and the second span stall; compressor surge). The firest and the second stall; compressor surge). 各位一种美国的 紅旗 通識 蒙蒙 康 斯斯斯斯斯特克 机电影 医二氏征

The state of the s (such as General Electric LM 5000) as part of a power plant, the first signs of a compressor full stall leading to a later shut down of a gas turbine can be 25 identified by observing the characteristic peak more than half an hour before the actual shut down. Within this context, the invention provides for an early warning of a stall condition so that appropriate measures to avoid engine stall can be undertaken.

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The frequency signal may easily be derived from the detector signals by 30 using common evaluation techniques, for example fast Fourier transformation (FFT) or fast Hartley transformation (FHT). No model calculations are necessary.

The pressure fluctuations due to the wake regions of the rotating blades 35 can best be measured by said pressure sensing device being arranged at said housing between the rotor blades and the stator blades of the respective compressor stage.

The frequency may be obtained by fast Fourier transformation, the respective electronic transformation units being readily obtainable. For the process according to the invention only the time varying part of the absolute pressure is of interest. These pressure fluctuations may be directly measured by means of a piezoelectric, a piezo- resistive pressure sensor or especially a piezocapacitive pressure sensor. Another less preferred pressure sensing device is a strain gauge pressure sensor.

The peak parameter indicative of the form of the characteristic peak may be the peak height or the peak width. In both cases, the parameter is easy to determine and easy to be compared with a limit value or with the limits of an allowed region.

In order to enhance the accuracy and/or to reduce the evaluation efforts, the frequency interval in which the frequency signal has to be evaluated, is determined to have a reduced width of less than 4000 Hz. A preferred width is 2000 Hz so that the frequency signal has to be determined only between the characteristic frequency minus 1000 Hz and the characteristic frequency plus 1000 Hz.

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At was found out that the observation of two characteristic peaks and the state of assigned to two different stages of the compressor enhances the sensitivity of the monitoring process. At high compressor rotational speed the load of the 25 stages increases in the down stream direction, that is that stage nearest to the high pressure axial end of the compressor is subjected to the highest load at high speed. When the compressor is driven in a region near the maximum possible load, the last stage usually is in the separation flow pre-stall condition, so that the corresponding characteristic peak is very small or is hidden by the 30 background signal. Depending on the actual fluid flow status of the compressor, the characteristic peak in next to the last stage may decrease with increasing load in contrast to the second to the last stage in which the characteristic peak may rise with load. This is due to the growing tendency of separation in the next to the last stage and the increase of the wake regions in 35 the second to the last stage. Thus, the form of the characteristic peak in the mentioned two stages is in opposite direction such that also small changes in the fluid flow status can be detected.

Preferably said peak parameter is defined as a rated sum of individual peak parameters of each of said at least two different characteristic peaks, said individual peak parameters being determined by the peak shape of the respective characteristic peak. In this way, only one parameter is to be observed.

Depending on the special construction of the compressor and on the operational parameters, especially the rotational speed of the compressor, at least one of the stages (in general the last stage at the high-pressure end of the compressor) is in the separation flow pre-stall status (with the compressor being driven at maximum efficiency, that is near the upper limit of its mass flow rate).

When the actual performance of the compressor changes in a direction away from the maximum possible mass flow rate, the separation effect decreases and is accompanied by a corresponding increase of the characteristic peak for a specific stage. This increase may be used as an input for controlling the axial compressor in a way to increase the compressor load. In a similar manner, a decrease of the characteristic peak may be used for controlling the axial compressor in a way to decrease the compressor load. With increasing load, the characteristic peak in the second to the last stage first increases with a growth of the wake regions and then decreases with the beginning of the flow separation (pre-stall status). The monitoring of this tendency may serve as a basis for control of the compressor in the sense of avoiding an overload of the compressor, that is to avoid compressor stall or compressor surge and avoiding to operate the compressor in an uneconomic way too far below the optimum mass flow rate.

To facilitate the simultaneous observation of changes of several characteristic peaks, it is preferred to define a peak parameter as a rated sum of individual peak parameters of each of said characteristic peaks.

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The invention further relates to a device for monitoring of an axial compressor in accordance with the above-described process for the monitoring of an axial compressor. The invention also relates to a device for controlling an axial compressor in accordance with the above mentioned process for controlling an axial processor.

#### BRIEF DESCRIPTION OF THE DRAWINGS

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For a better understanding of the invention, reference is made to the following description and the drawings.

Figure 1 is a simplified graphic representation of an axial compressor as part of a gas turbine showing the location of dynamic pressure probes; 5 Figure 2 is a schematic representation of the compressor of Figure 1 illustrating the three final compressor stages at the highpressure end of the compressor; is a block diagram of the dynamic pressure probes Figure 3 connected to an evaluation unit: 10 illustrates a frequency signal with a characteristic peak; Figure 4 Figures 5a,b,c, show three successive forms of the characteristic peak of Figure 4 obtained by increasing the load starting with Figure 5a; 15

is a table for demonstrating the dependency of the form of Figure 6 the three last stages on load. DESCRIPTION OF THE PREFERRED EMBODIMENT

中海 接触 自己 20 看法整元的 Referring to the drawings, wherein equal numerals correspond to equal elements throughout, first reference is made to Figures 1 and 2 wherein a typical compressor part of a gas turbine engine is depicted (including the present invention). The compressor 10 is comprised of a low pressure part 12 25 and a high pressure part 14. Rotor blades 16 of the compressor are mounted on a shaft 18 of a rotor 20. Stator blades 22 (guide vanes) are mounted in a housing (casing) 24 of said compressor 10 and are therefore stationary. Air enters at an inlet 26 of the gas turbine engine and is transported axially to compressor stages of the compressor under increasing pressure to an outlet 28. 30 An axis 30 of said compressor is defined as the axis of rotation of the rotor 20. Although not shown, the present invention may also be employed in connection with a radial type compressor.

> Each of the mentioned compressor stages consists of two rows of blades 35 with equal blade number, namely a row of rotor blades 16 and a row of stator blades 22. The blades of each row are arranged one following the other in a circumferential direction with respect to said axis 30. Figure 2 shows the last stage of the compressor at its outlet 28 (high pressure axial end of the

compressor) with rotor blades 16a and stator blades 22a. Also, the second-last and the third last compressor stages are depicted with rotor blades 16b and stator blades 22b and rotor blades 16c and stator blades 22c, respectively.

The compressor 10, according to Figure 1, comprises an accessory gear box 30 enabling the adjustment of orientation of blades in order to change the load of the respective stages. Figure 1 further shows a bleed air collector 31 between the low pressure part 12 and the high pressure part 14. As the compressor, used in connection with the invention, is of common construction, it is not necessary to go into further detail.

According to the invention, several pressure sensing devices in form of dynamic pressure sensors, are mounted in the axial gaps between rotor blades 16 and stator blades 22 of stages of the high pressure part 14 of compressor 10. 15 According to the most preferred embodiment, shown in Figures 1 and 2, these dynamic pressure sensors are mounted in the last three stages nearest the outlet 28 of the compressor 10. The dynamic pressure sensor associated to the last stage is indicated with 32a and the following dynamic pressure sensors (in the control of t the downstream direction of the compressor 10) with 32b and 32c. An inlet in the compressor 10 with 32b and 32c. 20 opening 35 of each sensor 32 is flush with an inner circumferential face 34 of a serving 5 to 5 wall 36 defining said housing 24. In this way, each sensor 32 measures the analysis of the same said pressure fluctuations of the respective stage, occurring at the inner and the stage of the stage circumferential face 34. Since the respective sensor 32 is located in the region of the axial gap between the rows of rotor blades 16 and stator blades 22, 25 following the rotor blades downstream, each sensor is sensitive for the so called wake regions (Dellenregionen) being developed by the axial air flow at the downstream edge 38 of each rotary blade. These wake regions rotating with the respective rotary blade 16 are regions with lower density and flow velocity and with varying flow direction. Instead of directly mounting the respective sensor 30 32 in an opening 40 (borescope hole), it is also possible to use an elongated adaptor (not shown) which, with one of its ends, is mounted to the opening 40 and, at its other end, carries the sensor.

The illustrated location of the sensor 32 at the high- pressure axial end of the high pressure part 14 of the compressor 10 is preferred for a compressor operating at high speed (design speed). For lower speeds or for changing operational conditions, pressure sensors may be mounted in the axial gaps between rotor- and stator blades at the other axial end of the high pressure part

14 of compressor 10. Also, more than three sensors may be employed, as shown in Figure 3, with a fourth sensor 32d. The minimum is one sensor. Dynamic pressure sensors, preferably piezoelectric pressure sensors, are used because of their reliability, high temperature operability and sensitivity for high frequency pressure fluctuations up to 20 000 Hz (for example Kistler Pressure Sensor, Type 6031).

As shown in Figures 2 and 3, each sensor is provided with an amplifier 42, amplifying the respective sensor signal. These amplifiers 42 are connected via lines 44, 46 to an evaluation unit 48.

As shown in Figure 3, the evaluation unit 48 contains several Fast Fourier Transformer (FFT) analyzers 50 which respectively receive signals from the mentioned amplifier 42a-42d through analogue digital converters ADC (or multi- plexers) 52a-d which are connected between each of the respective amplifiers (AMP) 42a-d and FFT analyzers 50a-d.

The signals from the FFT analyzers 50a-d are transmitted to a computer unit 54 comprising several subunits, amongst them a stall detector 56, the 20 functioning of which is described above. Besides this stall detector 56, further detectors for the status of the compressor may be installed, for example a contamination detector 58 for detecting fouling of the blades of the low pressure part 12 of compressor 10 and a blade excitation detector 60 for detecting pressure fluctuations which are able to induce high amplitude blade vibrations, which vibrations may damage the compressor. However, the stall detection according to the present invention, may also be performed independently of contamination detection and blade excitation detection.

In order to facilitate the computing of the frequency signals outputted from the FFT analyzers 50a-d, a unit 62 for signal preparation may be connected between the FFT analyzers 50a-d and the detectors 56, 58, 60. The unit 62 contains filter algorythms for handling and smoothing raw digital data as received from the FFT analyzers. A control program periodically switches the sensor signals of each of the individual dynamic pressure sensors 42a-d via the ADC-52a-d to the FFT analyzers 50a-d. The resulting frequency signals from the FFT analyzers, after smoothing via unit 62, are forwarded to said detectors 56, 58, 60 for comparison with respective reference patterns. If the comparison analysis indicates deviations beyond a predetermined allowable

threshold of difference, the computed evaluation is transmitted to a status indicating unit 64 to indicate contamination or stall or blade excitation. Thus, the operation and status of compressor 10 can be monitored. Independent of this monitoring, it is further possible to use the computed evaluation for controlling purposes. A respective compressor control unit 66, connected to evaluation unit 48, is also shown in Figure 3 serving for controlling the compressor 10. In case of an unnormal status of the compressor, detected by one of the detectors 56, 58, 60, the compressor control unit 66 takes measures to avoid the risk of damaging compressor 10, for example by lowering the load 10 (adjustment of orientation of blades by means of gear box 30 or by reducing the fuel injection rate of the combustion section to reduce the rotational speed). In some instances, the compressor control unit 66 may stop the compressor 10.

In the detectors 56, 58, 60, the smoothed frequency signal is evaluated, said 15 frequency signal being indicative of the amplitudes of frequency components of the respective sensor signal in a respective frequency interval.

The stall detector 56 examines the frequency signals in a specific frequency region around a specific frequency, the so called characteristic frequency C, 20 said frequency. C being defined as the product of the present rotational speed n of rotor 20 and the blade number z of the rotor blades of the respective compressor stage:

$$C = n * z \tag{1}$$

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The frequency interval around c may have a width of less than 4000 Hz and preferably is 2000 Hz so that the upper limit UL may be C + 1000 Hz and the lower limit LL may be C-1000 Hz (see Figure 5). In general, the blade number of rotor blades equals the blade number of stator blades within the 30 same stage.

The wake regions rotating with rotor blades 16 of the respective compressor stage are passing the sensor 32 with the characteristic frequency c. Therefore, the frequency signal shows a respective characteristic peak 70 at 35 C. It has been found, that the form of this characteristic peak is varying in a characteristic manner, if the load of the respective stage is increased starting from a normal stage load with peak 70a shown in Figure 5A. In a first phase, the peak becomes more characteristic as shown in Figure 5B (peak 70b). Both

the height and the width of the characteristic peak increase as the load increases. This behavior is due to an increase of the wake regions (Dellenregionen) of the rotating blades, producing more characteristic pressure variations with the characteristic frequency at the location of the respective sensor 32.

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However, with further increasing load, the peak height rapidly decreases and the peak is covered by the sloped background line 72. This behavior is due to the separation of parts of the boundary layers of the rotating blades 16.

10 These separated parts of the boundary layers are moved radially outwards to the inner circumferential face 34 of the housing 24 under the influence of rotational forces exerted by the rotor 20. Here, the swirled separated regions are collected to form a relatively thick layer with stochastic fluctuations. This layer shields sensor 32 from the pressure fluctuations of the wake regions so that the characteristic peak measured by this sensor decreases rapidly and is covered by the background line 72. This separation phase may be called separated flow pre-stall phase since the separation of boundary layers and the collection of separated flow regions at the inner circumferential face 34 does not remarkably reduce the pressure ratio of the respective stage. Stall effects

20 (rotating stall) with microscopic areas (bubbles) with blockage of flow in most cases will be observed when the characteristic peak has vanished (Figure 5c).

The observation of the characteristic peak therefore is a sensitive tool for monitoring and/or controlling of a compressor. One possibility of detecting changes of the form of the characteristic peak 70 would be a comparison of a predetermined peak form by means of pattern recognition. However, the evaluation is simplified, if not the complete peak form, but only one peak parameter is being observed and compared with limit values. This peak parameter may be defined as the peak height Amax above the background line 72 or the peak width 2-1 as shown in Fig. 4.

For a sensitive monitoring or controlling of the compressor, several characteristic peaks of different stages may be observed. In a most preferred embodiment, designed for monitoring and/or controlling of the compressor at design speed, the characteristic peaks of the last three stages of the high pressure part 14 are observed. In the present embodiment, the last stage is the 13th stage so that the respective peak parameter (especially peak height) is called p13. Consequently, the other two peak parameters are called p12 and

p11. The table in Figure 6 indicates the behaviors of the peak parameters p13, p12 and p11 with increasing load, wherein the upwardly oriented arrows indicate increasing and the downwardly oriented arrows indicate decreasing load and peak height, respectively with the number of arrows indicating the respective strength. The column at the utmost right is called "stall level", said stall level (general peak parameter) being expressed by the following formula:

a b
$$SL = ---- + ---- + c * p11$$
p13 p12 (2)

Experiments, performed with a compressor of a gas turbine of type LM 5000, show that in the last compressor stage separation is present at almost all times if the gas turbine is operated at its full speed operation mode under normal flow conditions. The load L2 of the respective stages in this case is indicated in line 2 of Figure 6. However, when lowering the load to a value L1 (Line 1 in Figure 6), the separation in stage 13 vanishes so that the characteristic peak develops, starting from Figure 5c to characteristic peak arrows on Figure 6. At the same time, the characteristic peak in stage 12 decreases from peak form 70b to peak form 70a (Figures 5B and 5A). The peak form 70a of the 11th stage remains unchanged. The above mentioned peak parameter SL according to equation 2 decreases with decreasing load from L2 to L1 since coefficient a is larger than coefficient b so that the contribution of the reciprocal value A/p13 exceeds the contribution of the reciprocal value B/p12.

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On the other hand, when increasing the load from the normal value L2 to a value L3, the characteristic peak of stage 13 is unchanged (form according to Fig. 5d); the characteristic peak of stage 12 develops from Fig. 5b to 5c and the characteristic peak of stage 11 develops from Fig. 5a to 5b. In dependence on parameters A, B, C, the peak parameter more or less sharply increases as shown in Figure 6, right hand side.

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Upon further increasing load to value L4, characteristic peaks of stages 12 and 13 remain unchanged (Figure 5d), whereas the characteristic peak of

stage 11 changes from Fig. 5b to Fig. 5d. Consequently, the peak parameter decreases.

In dependence upon the operation mode and compressor type used, the
risk of compressor stall or compressor surge is negligeable with loads L1 and
L2, comparatively low with load L3 and high with load L4. Therefore, a
monitoring or controlling of the compressor to avoid the risk of stall or surge is
possible by observing parameter SL and outputting an alarm signal if a certain
upper threshold value TU is exceeded by the actual peak parameter SL. In
order to avoid operation of the compressor in an uneconomic way below the
maximum possible load value, a low threshold value TL could be defined by
delivering an alarm signal if the actual peak parameter value SL becomes
lower than TL. In both cases, evaluation unit 48, according to Figures 2 and 3,
delivers the respective alarm signal to the status indicating unit 64 for
informing the service staff appropriately.

The peak parameter SL may also be used for closed-loop- control of the compressor. If the measured peak parameter SL leaves the allowed region between the lower threshold TL and the upper threshold TU, the compressor control unit receives the respective control signal in order to change one or more operational parameters of the compressor to change the load of the compressor into the desired direction.

By using equation 2 accordingly, load L4 is avoided, meaning a separation effect in stage 11 is avoided, since then stall is expected to occur. The stability limit therefore lies between load L3 and load L4.

However, if the stability limit is only reached after the separation has started in stage 13 (load L4), the following equation (3) for the peak parameter is preferred:

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Since the characteristic peaks increase in importance from stage 13 to stage 11, coefficient C is chosen to be larger than coefficient B and coefficient B is chosen to be larger than coefficient A.

Claims:

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1. Process for monitoring of a compressor (10), said compressor comprising a rotor and a housing, said rotor being rotatably mounted within said housing for rotation about a rotational axis with variable or constant rotational speed, said compressor further comprising at least one compressor stage, each of said at least one stages comprising a row of rotor blades mounted on said rotor and being arranged one following the other in a circumferential direction with respect to said rotational axis and of a row of stator blades mounted on said housing and being arranged one following the other in a circumferential direction with respect to said rotational axis, said process comprising the following steps:

- a) measuring of pressure fluctuations within at least one of said compressor stages in the region of said housing by means of at least one pressure sensing device, each device delivering a sensor signal, respectively;
- deriving a frequency signal from each of said sensor signals, said frequency signal being indicative of amplitudes of frequency components of said respective sensor signals in a respective frequency interval;
- checking whether each of said frequency signals comprises at least one characteristic peak in a region of a characteristic frequency assigned to one of said compressor stages, respectively and determining at least one peak parameter indicative of the form of said characteristic peaks, said characteristic frequency being defined as the product of said rotational speed and the blade number of the rotor blades of the respective compressor stage;
  - d) generating a status change signal indicative of a change of operational status of said compressor in case of said peak parameter having a value lying beyond a determined value range.

- 2. Process according to claim 1, wherein said pressure sensing device is arranged at said housing between the rotor blades and the stator blades of one of said compressor stages.
- 35 3. Process according to claim 1, wherein said frequency signal is obtained by fast Fourier-transformation (FFT).

4. Process according to claim 1, wherein said frequency signal is obtained by fast Hartley transformation (FHT).

- 5. Process according to claim 1, wherein said pressure sensing device comprises a piezoelectric or piezoresistive pressure sensor.
  - 6. Process according to claim 1, wherein said peak parameter is indicative of the peak height of the characteristic peak.
- 7. Process according to claim 6, wherein the peak height is defined as the ratio of a difference of a maximum value of said frequency signal in the region of said characteristic frequency and a mean value of said frequency signal within said predetermined frequency interval to said mean value.
- 15 8. Process according to claim 1, wherein said peak parameter is indicative of a peak width of said characteristic peak.
- Process according to claim 8, wherein said peak width is defined as
- Process according to claim 1 wherein said predetermined who have the said predetermined who have the said of the said predetermined who have the said the sa
  - 11. Process according to claim 10, wherein said predetermined frequency interval has a width of 2000 Hz.
  - 12. Process according to claim 1, wherein step c) is performed for at least two different characteristic peaks with different characteristic frequencies assigned to at least two different compressor stages, respectively, and wherein said status change signal according to step d) is generated in case that the peak parameter of at least one of said at least two characteristic peaks has a value lying beyond a determined value range assigned to the respective characteristic peak.
  - 13. Process according to claim 12, wherein said at least two different characteristic peaks are part of the frequency signal derived from the sensor signal of a single pressure sensing device.

14. Process according to claim 12, wherein said at least two different characteristic peaks are part of respective frequency signals, each derived from respective sensor signals of at least two pressure sensing devices.

- 15. Process according to claim 1, wherein step c) is performed for at least two different characteristic peaks with characteristic frequencies assigned to at least two different compressor stages, respectively and wherein said peak parameter is defined as a weighted sum of individual peak parameters of each of said at least two different characteristic peaks, said individual peak parameters being determined by the peak shape of the respective characteristic peak. 16. Process according to claim 15, wherein at least one of said individual peak parameters is defined by the reciprocal of the peak height of the respective characteristic peak.
- 5 17. Process according to claim 15, wherein at least one of said individual peak parameters is defined by the peak height of the respective peak parameter.

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- 18. Process according to claim 15 for monitoring of an axial

  compressor, wherein said peak parameter is defined as a weighted sum of a

  reciprocal of the peak height of the characteristic peak assigned to a last

  pressure stage nearest to a high-pressure axial end of said axial compressor, the

  reciprocal of the peak height of the characteristic peak being assigned to the

  second to the last pressure stage and the peak height of the characteristic peak

  assigned to the third to the last pressure stage.
  - 19. Process according to claim 15 for monitoring of an axial compressor, wherein said peak parameter is defined as a weighted sum of the reciprocals of the peak heights of the characteristic peaks assigned to a last pressure stage nearest to a high-pressure axial end of said axial compressor, to the second to the last pressure stage and to the third to the last pressure stage.
  - 20. Process for controlling of a compressor, said compressor comprising a rotor and a housing, said rotor being rotatably mounted within said housing for rotation about a rotational axis with variable or constant rotational speed, said compressor further comprising at least one compressor stage, each of said at least one stages comprising a row of rotor blades mounted on said rotor and being arranged one following the other in a circumferential

direction with respect to said rotational axis and of a row of stator blades mounted on said housing and being arranged one following the other in a circumferential direction with respect to said rotational axis, said process comprising the following steps:

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- measuring of pressure fluctuations within at least one of said a) compressor stages by means of at least one pressure sensing device, each device delivering a sensor signal, respectively;
- deriving a frequency signal from each of said sensor signals, said **b**) frequency signal being indicative of amplitudes of frequency components of said respective sensor signals in a respective frequency interval; characterized in the following further steps:
- checking whether each of said frequency signals comprises at least c) one characteristic peak in a region of a characteristic frequency assigned to one of said compressor stages, respectively and determining at least one peak parameter indicative of the form of said characteristic peaks, said characteristic frequency being defined as the product of said rotational speed and the blade number of the rotor blades of the respective compressor stage;
- d) generating a status change signal indicative of a change of 20 operational status of said compressor in case of said peak parameter having a value lying beyond a determined value range;

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- e) using said status change signal for controlling said axial compressor.
  - Device for monitoring of a compressor said compressor comprising 21. 25 a rotor and a housing, said rotor being rotatably mounted within said housing for rotation about a rotational axis with variable or constant rotational speed, said compressor further comprising at least one compressor stage, each of said at least one stages comprising a row of rotor blades mounted on said rotor and 30 being arranged one following the other in a circumferential direction with respect to said rotational axis and of a row of stator blades mounted on said housing and being arranged one following the other in a circumferential direction with respect to said rotational axis, said device comprising at least one pressure sensing device for measuring of pressure fluctuations within at 35 least one of said compressor stages, said pressure sensing device delivering a sensor signal, at least one transformation unit for deriving a frequency signal from each of said sensor signals, said frequency signal being indicative of amplitudes of frequency components of said respective sensor signals in a

respective frequency interval, a status detection unit for generating a status change signal indicative of a change of operational status of said compressor, said status detection unit being adapted for checking whether each of said frequency signals comprises at least one characteristic peak in a region of a characteristic frequency assigned to one of said compressor stages, respectively and determining at least one peak parameter indicative of the form of said characteristic peaks, said characteristic frequency being defined as the product of said rotational speed and the blade number of the rotor blades of the respective compressor stage and for generating said status signal in case of said peak parameter having a value lying beyond a determined value range, a status indicating unit receiving said status change signal and indicating the respective operational status of said compressor.

- 22. Device according to claim 21, wherein said pressure sensing device is arranged at said housing between the rotor blades and the stator blades of one of said compressor stages.
- 23. Device according to claim 21, wherein said pressure sensing device comprises a piezoelectric or piezo-resistive pressure sensor.
- 24. Device according to claim 21, wherein said transformation unit
  - 25. Device according to claim 21, wherein said transformation unit comprises a fast Hartley-transformation unit.
  - 26. Device for controlling of a compressor said compressor comprising a rotor and a housing, said rotor being rotatably mounted within said housing for rotation about a rotational axis with variable or constant rotational speed, said compressor further comprising at least one compressor stage, each of said at least one stages comprising a row of rotor blades mounted on said rotor and being arranged one following the other in a circumferential direction with respect to said rotational axis and of a row of stator blades mounted on said housing and being arranged one following the other in a circumferential direction with respect to said rotational axis, said device comprising at least one pressure sensing device for measuring of pressure fluctuations within at least one of said compressor stages, said pressure sensing device delivering a sensor signal, at least one transformation unit for deriving a frequency signal

from each of said sensor signals, said frequency signal being indicative of amplitudes of frequency components of said respective sensor signals in a respective frequency interval, a status detection unit for generating a status change signal indicative of a change of operational status of said compressor, said status detection unit being adapted for checking whether each of said frequency signals comprises at least one characteristic peak in a region of a characteristic frequency assigned to one of said compressor stages, respectively and determining at least one peak parameter indicative of the form of said characteristic peaks, said characteristic frequency being defined as the product of said rotational speed and the blade number of the rotor blades of the respective compressor stage and for generating said status signal in case of said peak parameter having a value lying beyond a determined value range, said status detection unit delivering said status change signal to a controlling unit for operational control of said axial compressor.

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27. Device according to claim 26, wherein said pressure sensing device is arranged at said housing between the rotor blades and the stator blades of one of said compressor stages.

20. 28. Device according to claim 26, wherein said pressure sensing device comprises a piezoelectric or piezo-resistive pressure sensor.

29. Device according to claim 26, wherein said transformation unit comprises a fast Fourier-transformation unit.

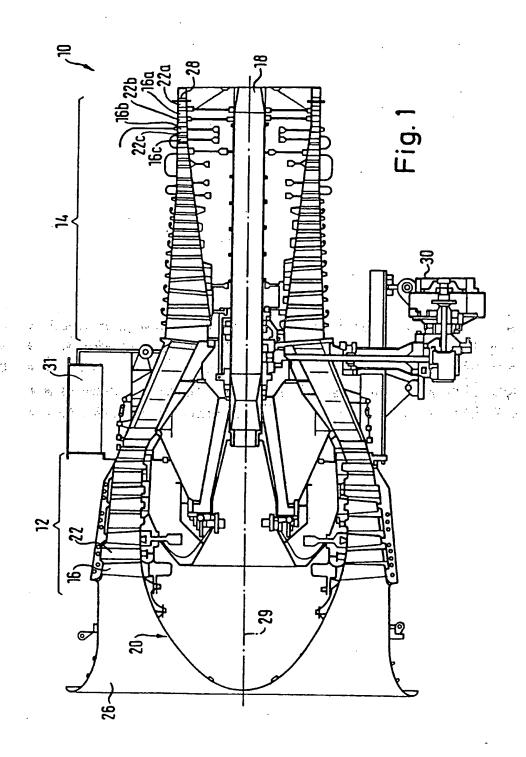
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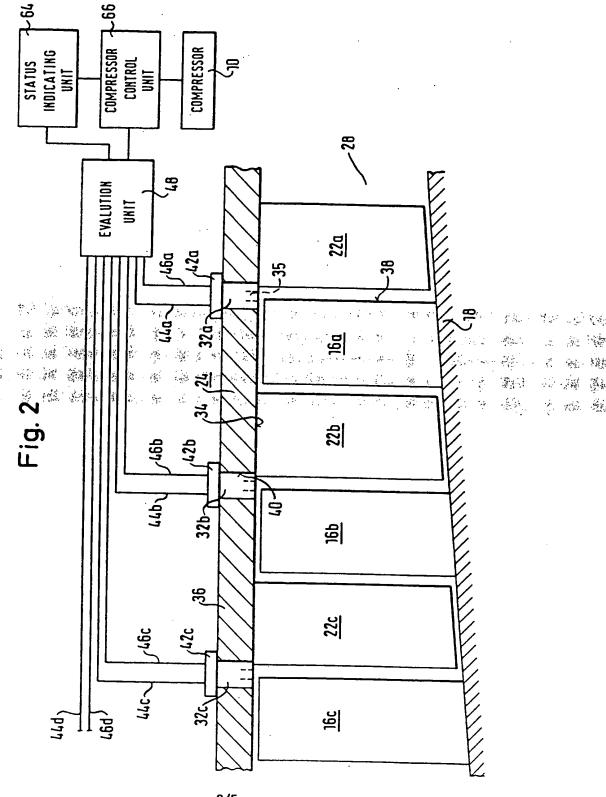
30. Device according to claim 26, wherein said transformation unit comprises a fast Hartley-transformation unit.

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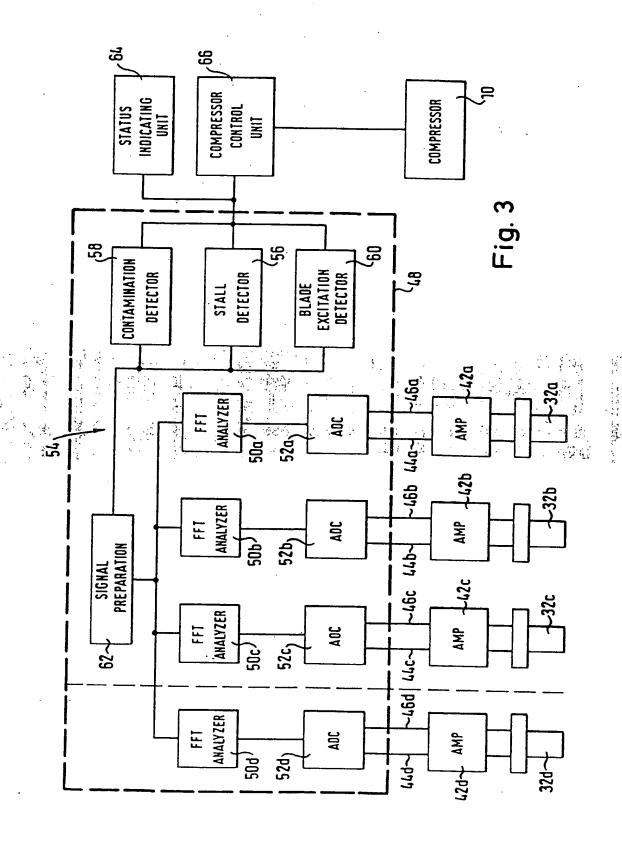
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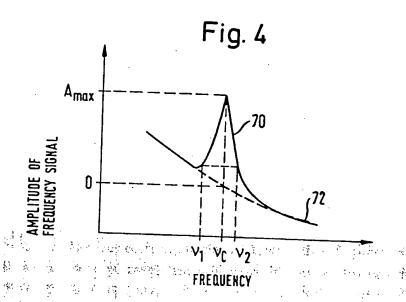
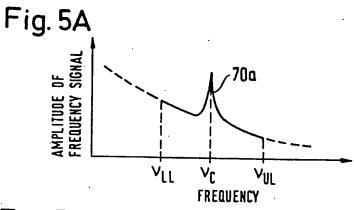
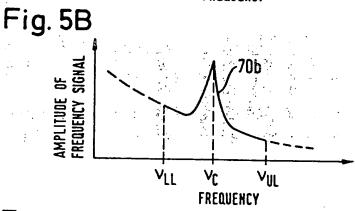
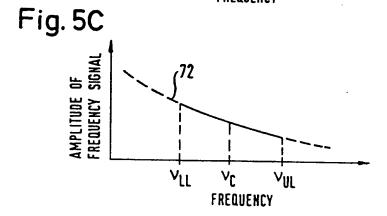


Fig. 6

LOAD	p 13	p 12	p 11	STALL-LEVEL	PP TI TII
L1	f f	1	1	_	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \
L2 † †	11	11	1	_	
L3	++	11	11	1	
L4 ++++	11	++	++	44	')







## INTERNATIONAL SEARCH REPORT

International application No. PCT/US93/05764

A. CL.	ASSIFICATION OF SUBJECT MATTER		·
IPC(5)	:G06F 15/20		
US CL	:364/558, 431.02; 73/116, 660; 415/26	•	
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C. DOC	CUMENTS CONSIDERED TO BE RELEVANT		
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